



# CATALOGUE STEPPER MOTORS ELECTRONICS

# **CONTROL** for all Dimensions





















Edition 2016 April

# Phytron GmbH

## Stepper motor technology for special requirements:

Stepper motor technology is particularly suitable for precision applications under extreme environmental conditions. Whether vacuum, cryo environment, high temperature or under the influence of radioactivity - the phytron **motor series** are tough and do precision work, because stepper motors can position very accurately without a fragile feedback encoder.

Our **control units** perform, especially in applications that rely on very precise and smooth running behaviour. We control motors in electron microscopes, accelerator experiments or also in paper production machines - with up to 1/512 step (102 400 positions per revolution with a 200 step motor). From the power amplifier to the modular, cost-effective multi-axis system we offer the right control concept for your requirements. You remain flexible with phytron, because we supplement the interest in and the ability of our customised products by developing them further. Customers from different industry sectors rely on our decades of experience in highly demanding application fields.

# Why buying a phytron product is always a good decision:

We are a customer-oriented high-technology company certified to ISO 9001 and EN13485. We have the process know-how of more than 300 stepper motors in space operations for the successful development of your demanding application!

We offer best service we also ask the right questions at the right time. Our Competence Center guarantees targeted consultation and therefore the early identification of requirements and any potential problems.

Based on our proven products used in the series, we develop solutions that provide precision work for our customers with extreme reliability. Whether for extreme environmental conditions or as a perfect fit for your particular application - phytron motors are always a good choice!

phytron combines the flexibility and client-specific consulting from a niche player with the efficiency and standardised quality assurance processes of series production. As quality conscions business we produce in Gröbenzell near Munich.



General Manager

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Stand-alone units are stepper motor controllers with an intelligent processor. You can execute sequential programs and the unit can operate via Host interface or also stand-alone.



# *phy***MOTION**™

Free programmable, modular multi axes controller for stepper motors



#### MCC-2 LIN

Free programmable controller for two axes with linear power stages



# MCC-2

Free programmable controller for two axes



# MCC-1

Free programmable controller for one axis

# DRIVES



Drives contain so-called indexers and power stages. You put instructions in a programming language to control signals, which boosts the internal power stage.



#### 1-STEP-DRIVE-5A-48V

Stepper motor module with integrated power stage for the SIMATIC ET 200<sup>®</sup>S

# **POWER STAGES**





Stepper motor power stages are reinforce Control pulses/Motor direction or SIN/COS signals and directly control the stepper motor.



## APS

High performance stepper motor power stage module



# MSX

19" stepper motor power stage module for high performance



#### ZMX<sup>+</sup>

19" stepper motor power stage module with ServiceBus



19" sub-rack with plug-in stepper motor power stage modules



#### MCD<sup>+</sup>

Compact stepper motor power stage with ServiceBus

# POWER SUPPLIES





## SPH 240 / 500 / 1013

Power supply for stepper motor power stages and -controllers





# USB-485 Converter

Interface converter as stick for Phytron stepper motor controllers and power stage

# SOFTWARE

Our free WINDOWS  $^{\otimes}$  programs allow to program, to monitor and to adjust power stages and controllers comfortable and clear via PC.



## *phy***LOGIC**<sup>™</sup> ToolBox

Development environment for the phyMOTION  $^{\mbox{\tiny TM}}$  stepper motor controller



#### ServiceBus-Comm<sup>™</sup>

Communication software for stepper motor power stages

## Phytron GmbH

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www.phytron.eu

# STAND-ALONE UNITS

Stand-alone Units are stepper motor controllers with an intelligent processor. You can execute sequential programs and the unit can operate via Host interface or also stand-alone.

POWER SUPPLY CPU INDEX POWER STAGE



# *phy***MOTION**<sup>™</sup>

Free programmable, modular multi axes controller for stepper motors



MCC-2

Free programmable controller for two axes



MCC-2 LIN

Free programmable, linear controller for two axes



MCC-1

Free programmable controller for one axis





The phyMOTION<sup>TM</sup> combines PLC and motion control functions into a flexible and convenient framework for multi axis stepper motor applications. The free software *phy***LOGIC**<sup>™</sup> Toolbox, the LabVIEW interface, the Androidbased touch interface (internal/external) and the open protocol for controller drive and parameterising create additional scope for development. The integra-

ted, high resolution power stages up to 15 A<sub>Peak</sub> at 120 V<sub>DC</sub> simplify the wiring significantly.

#### Designed for Industry 4.0

The *phy***MOTION**™ can be operated below existing PLC systems as a slave system, as distributed intelligence or as a stand-alone motion control solution. Online parameterising and -diagnostics are also standard feature as limit switch/reference switch inputs per axis. Each axis can be expanded with encoder (Endat, SSI- /Quadrature) and temperature evaluation. Besides standard PLC functions such as analogue and digital I/Os, a variety of interfaces (Ethernet, Profibus, Profinet, RS232/485, USB, Bluetooth) the phyMOTION™ also provides linear and circular interpolation.

Extreme. Precision. Positioning.



#### Edition 2016 January

#### Module selection for your *phy*MOTION<sup>™</sup>

To make the module selection as comfortable as possible, we coded the modules by main and auxiliary functions.



This main function is included in the respective module.



The main function is not available in the



I/O D Auxiliary functions are shown only if the module supports them.



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\* means the main or auxiliary function is selectable as option.

Main functions	SUPPLY	(power supply unit).							
	CPU	Modules with CPU contain intelligent processors and can execute the total sequential programs and enable the $phy$ MOTION <sup>TM</sup> to drive in stand-alone mode.							
	INDEX	The INDEXER represents the functionality to generate signals from commands of a pro- gramming language, which the power stage can amplify. Normally, the signal is control pulses/direction or SIN/COS.							
	POWER STAGE	POWER STAGE represents a stepper motor amplifier. Incoming control pulses/direction or SIN/COS signals are amplified and output to the motor							
iliary functions	ENC	Encoder evaluation	POW IN	Power distribution					
	TEMP	Motor temperature evaluation	СОМ	Host interface					
	I/0 D	Digital inputs and/or outputs	SAFETY	Safe Torque Off					
	I/0 A	Analogue inputs and/or outputs							
Aux									

POWER The POWER SUPPLY function is marked when there is a nower supply in the module

# Housing and Supply

# Housing types of the *phy***MOTION**<sup>™</sup>:



Bench or rail mounting



Rack mounting (connection side is the front)



Wall mounting or rack-inverse (like rack mounting, but connection side is back)

Type / current supply	Slots	U	Width	Height	Depth	Mounting
	6	24	137	132.5 1		R/W/MR/D
c / oxtornal	8	32	177.6		121	
S / externat	10	40	218.3			
	21	84	442.4			
p / internal	21	84	442.4	132.5	360	R/RI/D
dimensions in mm Mounting bracket for rack, rack-inverse or wall mounting: +40.6 mm						

#### Jpe phyMOTION - 6SL - MR - s - X Options number of slots 6SL 6 slots 8SL 8 slots 10SL 10 slots 21 slots (=19") 21SL

mounting	W MR R D	wall mounting rail 19″ sub rack bench
housing depth	S	small
customised	Х	customer demand

Ordering c	ode "	'int"
phyMOTION	- 21ST -	iolo Adunting K Housing depth Customised
Options		
number of slots	21SL	21 slots (=19")
mounting	R RI D	19" sub rack rack-inverse bench
housing depth	р	power
customised	Х	customer demand



- 24  $\dot{V}_{DC}$  (10 A / 20 A), 48  $V_{DC}$  (5 A / 10 A / 20 A), 72 V<sub>DC</sub> (6.7 A / 13.5 A)
- Permanently short circuit-proof output
- Overvoltage protection primary and secondary side
- Overtemperature protection
- Integrated fan
- Dimensions (WxHxD) SPH240: 45 x 125 x 121 SPH500: 82 x 125 x 121 SPH1013: 66 x 230 x 183
- DIN rail or wall

Mating connectors are included in delivery.

240-2410

240-4805

500-2420

500-4810

500-7207

1013-4821

1013-7214

Н

W

Options

Output

power

Output

Mounting

0 OK

;; ;;

Line

POWER

STAGE

#### www.phytron.eu

 $24\,V_{\text{DC}}\,/\,10$  A

48 V<sub>DC</sub> / 5 A

24 V<sub>DC</sub> / 20 A

48 V<sub>DC</sub> / 10 A

72 V<sub>DC</sub> / 6.7 A

48 V<sub>DC</sub> / 20 A

72 V<sub>DC</sub> / 13.5 A

Rear DIN rail

Rear wall



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# 2 Host Interface

POWER SUPPL

# Main Controller (MCM01)

O MCM01 CPU Status LEDs 00 Reset +24 V Reset 0 V INDEX POWER STAGE Host Interface (0

# Intelligent CPU and bus:

- Main CPU:
- Controls and administers up to 64 modules - Program and register memory up to 4 MB
- Internal memory expandable with future memory
- modules
- Script program administration
- Firmware administration
- Elegant programming with *phy*LOGIC<sup>™</sup> and G-Code

0,

- Selectable communication interface:
  - CAN
  - Ethernet
- ProfiBus/ProfiNet
- RS 485, RS 232, RS 422
- Bluetooth

#### Main Controller (MCM02) POWER SUPPL • Main CPU: CPU



# Intelligent CPU, bus and supply:

- Controls and administers up to 64 modules
- 24 to 70  $V_{\mbox{\scriptsize DC}}$  supply voltage - Mini USB interface
- Program and register memory up to 4 MB
- Internal memory expandable with future memory
- modules
- Script program administration
- Firmware administration
- Elegant programming with *phy*LOGIC<sup>™</sup>
- Selectable communication interface:
- Ethernet
- ProfiBus/ProfiNet
- Bluetooth

#### in, Main Controller and Supply (MCM03) POWER SUPPLY Intelligent CPU, bus and for internal supply: O MCM03 • Main CPU: CPU - Controls and administers up to 64 modules Status LEDs -00 - Program and register memory up to 4 MB INDEX Local/Remote Ð - Internal memory expandable with future memory Reset -0 modules POWER +24 V<sub>DC</sub> OUT - Script program administration USB mini STAGE - Firmware administration - Elegant programming with *phy*LOGIC<sup>™</sup> • Selectable communication interface: - Ethernet, ProfiBus/ProfiNet, Bluetooth Host Interface • 24 V<sub>DC</sub> output (for e.g. sensors)





Mating connectors are included in delivery.



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# Power Stages, Indexer, I/Os (analog/digital) & HMI



## Indexer with integrated 3.5 A power stage

101

- Integrated indexer for standard functions:
  - Relative and absolute positioning
  - Reference movements/speed mode
  - Step frequency to 40,000 steps/second
- Integrated 3.5 A power stage
  - 3.5 A<sub>PEAK</sub> at 24 to 48 V<sub>DC</sub> (derating dep. on application)
- Selectable step resolution up to 1/256 step
- Online power stage parameterisation and diagnostics
- 3 limit/reference switches
- Optional encoder evaluation
  - SSI/ Quadratic Incremental (ECAS01) or Endat (ECES01); Resolver (ECMS01)
- Optional motor temperature evaluation - for Pt100 sensors (PTS01) or K types (KTS01)

#### 1 Axis Stepper Motor Drive (I1AM02) POWER SUPPLY Indexer with selectable APS power stage (0)11AM02 • Integrated indexer for standard functions: CPU - Relative and absolute positioning Status θO I FDs

Encoder\*/

Temp.

sensor

Stepper

motor

Limit Switch



- Step frequency to 40,000 steps/second
- Up to 5 A<sub>PEAK</sub> at 24 to 70 V<sub>DC</sub> (derating dep. on application)
- Selectable step resolution up to 1/256 step
- Online power stage parameterisation and diagnostics
- 3 limit/reference switches
- Optional encoder evaluation
  - SSI/ Quadratic Incremental (ECAS01) or Endat (ECES01); Resolver (ECMS01)
- Optional motor temperature evaluation - for Pt100 sensors (PTS01) or K types (KTS01)

#### 4 Axes High End Indexer (I4XM01) POWER SUPPL $\bigcirc$ Indexer module 14XM01 • 1, 2, 3 and 4 axes stepper motor indexer CPU Status • Circular interpolation for 2 any axes -00 LEDs Linear interpolation for 4 axes (also for reduction gears axes) Additional Control Pulses/Direction input and POWER Service output for "electronic wave" Bus STAGE • Expanded indexer functions: - Velocity/end position during the movement changeable Control - Variable, short ramps; high velocities pulses/ Direction - Interpolation also for gear axes Boost - High speed: up to 500,000 steps/second signals - ... (0)









\* see page 2



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#### <sub>ľybe</sub> EXAM01 - ECES01 - PTS01 Options Encoder ECES01 ENDAT encoder evaluation ECAS01 SSI/QUADR. encoder ECMS01 Resolver no encoder module PTS01 Pt sensor Temperature evaluation KTS01 K type no temperature module Mating connectors are included in delivery

Ordering Code





# Digital I/Os (DIOM01)

# Digital I/O module

- 8 digital inputs 24  $V_{DC}$
- 8 digital outputs 24 V<sub>DC</sub>, max. 1 A
- 24 V supply of the inputs and outputs is centrally delivered either by the power modules or directly at the DIOM01.
- DIOM01 can also be used as a single channel counter module.





\* see page 2









# HMI-Interfaces

# Android-based integrated Touch Panel (TPM01) Integrated human-machine interface ● 800 x 480 px - TFT display ● Integrated in the *phy*MOTION<sup>™</sup> housing ● Touch functionality ● As user interface i.e. for parameter selection ● For support, parameterisation and diagnostics





#### from 480 x 800 px (recommended: 7"-display) – TFT display

- For connection to the POWM01 main power module (Ethernet or WLAN) or to the MCM01/MCM02 module (Bluetooth)
- Touch functionality
- As user interface i.e. for parameter selection
- For support, parameterisation and diagnostics



Ordering Code	
The	
TPM01	





# Software



# Free of charge development environment

- Operating software and development environment for the phyMOTION<sup>™</sup> phytron controller
- Easy to program: Drawing and converting of 2D contours in *phy*LOGIC<sup>™</sup> commands (Motion Creator)
- Parameterising, programming, editing, debugging
- Support in the commissioning phase i.e. by test functions
- Display of status and graphical presentation of a current XY position
- Archiving of parameter sets and programs



# <section-header><section-header><image><image><image>



# Equipment

Motor Shield Clamp	Shielding for motor connection	# 10015002	
	<ul> <li>Easy to go</li> <li>Plug-in connection for motor shielding of the following modules of the phytron controller <i>phy</i>MOTION<sup>™</sup>: INAM-, EXAM-, 11AM01- or 11AM02- module</li> <li>On delivery: shielded clamp with cableties and screws</li> <li>The motor connectors are included in the package of your <i>phy</i>MOTION<sup>™</sup> controller.</li> </ul>		



Strain Relief for Motor cable

#### Mountable rail for strain relief of the motor cables

- Dimension: (482.6 x 44.5 x 8) mm
- Material: Aluminium
- 21 cable clamps
- Mountable at the 19"-switching cabinet with two M3 screws

## Ordering ID

Ordering ID

# 10019310



# Ordering ID

#### # 10019311

# 4 Order and Receive the Fully Assembled phyMOTION<sup>™</sup>

Configuration Example			in.
phyM0TI0N™ with internal supp	ly		
	Ordering	code example:	
		Ordering code	Description
	Housing	phyMOTION-21SL-R-p	19" subrack housing, housing depth 360 mm
	Modules	Ordering code	Description
	Slot 1	MCM03-ETHS01	Main controller with Ethernet interface, internal supply
	Slot 2	DIOM01	Digital I/O module
	Slot 3	DIOM01	Digital I/O module
° <b></b>	Slot 4	DIOM01	Digital I/O module
	Slot 5	I4XM01	4 axes indexer module
	Slot 6	INAM02-MSX-ECAS01	MSX power stage with Quadratic encoder evaluation
	Slot 7	INAM02-MSX-ECES01	MSX power stage with Endat encoder evaluation
	Slot 8	INAM02-MSX-ECAS01	MSX power stage with Quadratic encoder evaluation
	Slot 9	INAM01-APS01-ECES01-KTS	Internal 5 A power stage with Endat-Enc./Motor temp evaluation
	Slot 10 -19	-	blank front panels
	Slot 20	NETM01-230V-120V-120V-120V	Ext. mains voltage 230 V, 3 x 500 W for 120 V

# phyMOTION<sup>™</sup> with SLS



#### Ordering Code Example:

	Ordering code	Description			
Housing	phyMOTION-21SL-R-p	19"subrack housing, housing depth 360 mm			
Modules	Ordering code	Description			
Slot 1	POWM01	Main supply module			
Slot 2	MCM01-RSS485	Main controller with RS 485 interface			
Slot 3	I4XM01	4 axes indexer module			
Slot 4	EXAM01-ECAS01	Indexer interface for MSX power stage with Quadrencoder eval.			
Slot 5	EXAM01-ECAS01	Indexer interface for MSX power stage with Quadrencoder eval			
Slot 6	EXAM01-ECAS01	Indexer interface for MSX power stage with Quadrencoder eval			
Slot 7	EXAM01-ECES01-KTS	Indexer interface for MSX power stage with Endat-encoder-/ Motor temp. evaluation			
Slot 8	DIOM01	Digital I/O module			
Slot 9	DIOM01	Digital I/O module			

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# **APPLICATION in SCIENCE**



# Use for Vacuum Chambers





Vacuum chambers are the core of many modern research and production plants.

The phyMOTION<sup>TM</sup> offers additional functions for the control of also complex machines from outside the vacuum chamber such as temperature monitoring, encoder and resolver evaluation as well as linear and circular interpolation for high-precision positioning. The heating of the motors is minimised in the application by the high-quality power stage design.

The *phy***MOTION**<sup>TM</sup> with integrated power stages close to the vacuum chamber allows a low-noise monitoring of the temperatur sensors and a direct motor cable connection.

For large systems make sure that the automation for the vacuum actuators can be seamlessly integrated into the excisting PLC world despite the special requirements.

The integrated power stages can be optionally provided with temperature monitoring and encoder evaluation.

The integrated field bus interface allows both the control out of a PLC system SPS-System and the operation via spplied software, LabView interface or touch panel.

The phyMOTION<sup>TM</sup> is also successfully used in the research plant Max Planck Institute for Extraterrestrial Physics, Neuried for aligning optical systems in a vacuum.

The controller is controlled via Ethernet and LabView.



Configuration: *phy***MOTION**<sup>TM</sup> with external supply: MCM01, POWM01, POWM02, 2 x I4XM01, 6 x I1AM01, 2 x DIOM01

# **APPLICATION** in FOOD



# XY Alignment for Cutting Baked Wafer Blanks





The phy**MOTION**<sup>TM</sup> is part of the circular cutting machine for wafers. Here, the baking wafers are cut with a rotating circular blade out of the baked blanks

The radius-dependent, area optimisation XY positioning of the semi-finished goods under the punching knife is controlled by the phy**MOTION**<sup>TM</sup>.

The external touch panel allows a comfortable operation.



#### Configuration:

 $phy {\tt MOTION^{TM}}$  in combination with a plug-in power stage unit SLS with internal power supply: MCM02 with ETHS01, I4XM01, 2x INAM02, 1x DIOM01, 2x MSX152 power stages, external touch operator panel

¢t,

# Industrial

# Configuration Example

# 19" rack housing with internal supply and integrated touch panel: 4 axes with indexer and I/Os $\,$

Ordering Code Example:		
	Ordering Code	Description
Housing	<i>phy</i> <b>MOTION</b> -21SL-p	19" rack mounting housing with 10 slots, integrated touch panel and depth 360 mm
Module	Ordering Code	Description
TPM01	TPM01	Android-based integrated touch panel
Slot 1	POWM03	Main power supply
Slot 2	MCM03-PBS01	Main controller with ProfiBus interface
Slot 3	DIOM01	Digital I/O module
Slot 4	DIOM01	Digital I/O module
Slot 5	14XM01	4 axes indexer module
Slot 6	INAM01-APS01-ECAS01	Internal 5 A power stage with Quadratic encoder evaluation
Slot 7	INAM02-MSX-ECMS01	1 axis module for integrated MSX power stage with resolver
Slot 8	INAM02-MSX-ECMS01	1 axis module for integrated MSX power stage with resolver
Slot 9	INAM02-MSX-ECMS01	1 axis module for integrated MSX power stage with resolver
Slot 10	NETM01	230 V (115 V) supply with grounding connection if motor voltage >70 V

Configuration Example			
10-Slot housing for rack mo	ounting	4 axes with indexer	and I/Os
	Ordering C	Code Example:	
		Ordering Code	Description
O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O         O	Housing	phyMOTION-10SL-R-s	Rack mounting housing with 10 slots and depth 120 mm
	Module	Ordering Code	Description
	Slot 1	POWM01	Main power supply
	Slot 2	MCM01-RSS01	Main controller with RS 485 interface
	Slot 3	DIOM01	Digital I/O module
	Slot 4	DIOM01	Digital I/O module
	Slot 5	DIOM01	Digital I/O module
	Slot 6	14XM01	4 axes indexer module
	Slot 7	INAM01-APS01-ECAS01	Internal 5 A power stage with Quadratic encoder evaluation
	Slot 8	INAM01-APS01-ECES01	Internal 5 A power stage with ENDAT encoder evaluation
	Slot 9	INAM01-APS01-ECAS01-PTS	Internal 5 A power stage with Quadratic encoder- and motor temperature evaluation with PT sensor
	Slot 10	INAM01-APS01-ECES01-KTS	Internal 5 A power stage with ENDAT encoder- and motor temperature evaluation with K types
	Power supply	SPH240-2410-W	External power supply unit with 240 W, 24 $V_{\rm DC}$ output voltage and 10 A for rear wall
	Power supply	SPH240-4805-W	External power supply unit with 240 W, 48 $\rm V_{\rm DC}$ output voltage and 5 A for rear wall
	TPE	TPE	External Operator Touch Panel

All illustrations, descriptions and technical specifications are subject to modifications, no responsibility is accepted for the accuracy of this information.

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ENG www.phytron.eu/MCC-2

# MCC-2 Programmable controller for two axes

The MCC-2, phytron's freely programmable dual axis stepper motor controller, is a compact stand-alone unit (CPU, Indexer and power stage) for 2 phase stepper motors providing up to  $3.5 A_{\text{PEAK}}$  phase current.

Controllers in the MCC series have many inputs and outputs (digital and analog) and encoder inputs for step position monitoring plus possibilities to connect limit switches all as standard.

Due to the viariety of available host interfaces (Ethernet, Profibus, USB etc.), the MCC can

be quickly and easily integrated into existing applications.

This controller is easy to program and can operate either directly (remote) via its host interface or stand-alone (local) with the program routines stored within.

#### Applications

As a compact stand-alone device, it convinces expecially in small experimental setups, machines and equipment, which can be dispensed in a PLC.

Highlights		
1212	LabVIEW®	
	Stand-alone	
Stand-alone	Once programmed the MCC-2 can work without additional PC/controller.	
	PROFI®BUS	

# P PROFI®BUS

As suggested by our customers now with optional Profibus interface!

#### LabVIEW<sup>®</sup>

LabVIEW<sup>®</sup> is a simulation software with a graphical interface. Use the VIs (Virtual Instruments) generated by phytron and integrate them in your LabVIEW<sup>®</sup> project. So you can easily control the MCC from your usual programming environment.

#### MiniLog-Comm®

MiniLog-Comm<sup>®</sup> is phytron's communication software running under Windows<sup>®</sup> to facilitate programming of the stepper motor controller. It provides quick and easy generation of sequential programs.

MiniLog-Comm<sup>®</sup> software is delivered free with phytron controllers and offers additional functions for test mode, step by step control or single sequence command execution of a motor move, a motor status window and even a Motion Creator.



- 2 axes stepper motor control unit with integrated power stages
- Bipolar control of 2 phase stepper motors
- Phase currents up to 3.5 A<sub>PEAK</sub>
- Power supply 24 to 48 V<sub>DC</sub>
- Step resolution 1/1 up to 1/256 step
- Host interfaces: Ethernet, USB, Profibus, RS 485 or RS 232
- Interfaces:
  - 2 encoders
  - 2 analogue inputs
  - 8 digital inputs and 8 outputs
  - 4 limit switches
  - 2 redundant designed enable inputs
- Programming in well-tried MiniLog format, acc. to DIN 66025 or in LabVIEW<sup>®</sup>
- LabVIEW<sup>®</sup> driver for including the MCC in your LabVIEW<sup>®</sup> project
- Remote or local mode



Specification	
Mechanical	
Dimensions (W x H x D)	72 x 127 x 110 mm; 90 x 127 x 110 mm with attached USB converter or terminal adaptor
Weight	Approx. 950 g
Mounting	Wall- or rail mounting
Features	
Stepper motors	Suitable for the control of 2 phase stepper motors with 4, (6) or 8 lead wiring
Supply voltage	Controller and motor: 24 to 48 $V_{\text{DC}}$ ; Limit switches and outputs: 24 $V_{\text{DC}}$
Phase current	Up to 3.5 A <sub>PEAK</sub>
Step resolution	1/1, 1/2, 1/4, 1/5, 1/8, 1/10, 1/20; for smoother motor rotation: 1/32, 1/64, 1/128 up to 1/256 step of a full step
Step frequency	40,000 steps/sec
Hardware error detection	<ul> <li>Short circuit (between phase and power supply; between both phases; within a motor against ground))</li> <li>Over temperature</li> <li>Under voltage</li> </ul>
Cable length	Motor: shielded: 50 m max. Signal: shielded: 100 m max.
Diagnostic LEDs	Ready, busy, error
Operating mode	"Remote" - via bus; "Local" - stand-alone mode with sequence program
Interfaces	
Analogue outputs	2 x (A, B, C, D) for two 2 phase stepper motors
Digital outputs	8 digital outputs, overload-proof, each electrically isolated from power supply / 24 V power supply fed separately; the maximum load is 1 A on each output; 4 A for all outputs
Host interface	Optional: Ethernet, USB, Profibus, RS 485, RS 232
Analogue inputs	2 x 10 Bit AD converter e. g. for a joystick. The joystick power (5 V <sub>DC</sub> ; 100 mA max.) is provided by the controller
Digital inputs	<ul> <li>8 digital inputs, electrically isolated, 24 V input level</li> <li>4 limit switches: type PNP NCC or NOC</li> <li>2 encoders for optional differential incremental encoder or SSI absolute encoder; provided by the controller (5.3 V<sub>DC</sub>, max. 200 mA)</li> <li>2 Motor Enable</li> </ul>
Communication and P	rogramming
Programming	MiniLog format acc. to DIN 66025 – MiniLog-Comm <sup>®</sup> (included in delivery) – LabVIEW <sup>®</sup> VIs (included in delivery)
Memory	128 kB program memory
Operating Conditions	
Temperatures	Operation: +5 to +50 °C; storage and transport: -10 to +85 °C
Degree of pollution	Level 2
Relative humidity	5 to 85 %, class 3K3 non-condensing
Protection class	IP 20
EMC immunity/ EMC emission	Acc. EN 61000-3-2 Acc. EN 61000-6-1, -3, -4 Acc. EN 6100-4-26, -11
Approval	CE





Configurations



Ordering Code			
The variable elements of the product are displayed in colour.	Type Current / Chan-	Molor vollage Step resolution Host interface Mountrig Terminal adaptor	
Ordering code	MCC-2 - 32 - 48	3 MINI - <mark>USB</mark> - <mark>W</mark> - B	
Options			
Host interface	ETH USB RS 485 RS 485-USB RS 232 PB	Ethernet port USB port RS 485/4-wire port RS 485/4-wire + USB converter RS 232 port Profibus port	
Mounting	W H	Wall mounting With attached clip for DIN rail mounting	
Adaptor	В	RS 232 adaptor for BT 5 operator terminal	
Windows <sup>®</sup> is a trade mark of Microsoft. LabVIEW <sup>®</sup> is a trade mark of National Instruments Corporation.			

MiniLog-Comm<sup>®</sup> is a trade mark of Phytron GmbH.

PROFI<sup>®</sup>BUS is a standard of the PROFIBUS fieldbus organisation. (PI).

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# Extent of Supply

- A CD-ROM with MiniLog-Comm<sup>®</sup> software, LabVIEW<sup>®</sup> VIs and USB driver
- Connector set
- Mini USB-RS 485 converter

# **Optional Accessories**

- Cable assembly
- Power supply unit SPH 240-4805
- BT 5 operator terminal
- Mini USB-RS 485 converter

# Phytron GmbH

Industriestraße 12 – 82194 Gröbenzell T +49-8142-503-0 F +49-8142-503-190

#### www.phytron.eu



www.phytron.eu/MCC-2lin

The MCC-2 LIN, phytron's freely programmable dual axis stepper motor controller, is a compact stand-alone unit (CPU, Indexer and power stage) for 2 phase stepper motors providing up to 1.7 A<sub>PEAK</sub> phase current.

Controllers in the MCC series have many inputs and outputs (digital and analogue) and encoder inputs for step position monitoring plus possibilities to connect limit switches all as standard.

Due to the viariety of available host interfaces

(USB, Ethernet etc.), the MCC can be quickly and easily integrated into existing applications.

This controller is easy to program and can operate either directly (remote) via its bus or stand alone (local) with the program routines stored within.

#### Application

As a compact stand-alone device, it convinces expecially in small experimental setups, machines and equipment, which can be dispensed in a PLC.

#### Highlights

Stand-alone

(( )))

Low Noises

ENG



#### Stand-alone

Once programmed the MCC-2 LIN can work without additional PC/controller.

#### Low Noises

Low noises operation for sensitive applications for medical and scientific applications.

#### LabVIEW<sup>®</sup>

LabVIEW<sup>®</sup> is a simulation software with a graphical interface. Use the VIs (Virtual Instruments) generated by phytron and integrate them in your LabVIEW<sup>®</sup> project. So you can easily control the MCC from your usual programming environment.

#### MiniLog-Comm<sup>®</sup>

MiniLog-Comm<sup>®</sup> is phytron's communication software running under WINDOWS<sup>®</sup> to facilitate programming of the stepper motor controller. It provides quick and easy generation of sequential programs.

MiniLog-Comm<sup>®</sup> software is delivered free with phytron controllers and offers additional functions for test mode, step by step control or single sequence command execution of a motor move, a motor status window and even a Motion Creator.



- 2 axes stepper motor control unit with integrated power stages
- Use in EMC-sensitive applications possible
- Phase currents up to 1.7 A<sub>PEAK</sub>
- Power supply 24 to 48 V<sub>DC</sub>
- Step resolution 1/1 up to 1/256 step
- Host interfaces: USB, Ethernet, RS 485 or RS 232
- Interfaces:
- 2 encoders
- 2 analog inputs
- 8 digital inputs and 8 outputs
- 4 limit switches
- 2 redundant designed enable inputs
- Programming in well-tried MiniLog format, acc. to DIN 66025 or in LabVIEW<sup>®</sup>
- LabVIEW<sup>®</sup> drivers for including the MCC in your LabVIEW<sup>®</sup> project
- Remote or local mode



Specification		
Mechanical		
Dimensions (W x H x D)	108 x 127 x 110 mm; 126 x 127 x 110 mm with attached USB converter or terminal adaptor	
Weight	Approx. 1350 g	
Mounting	Wall or rail mounting	
Features		
Stepper motors	Suitable for the control of 2 phase stepper motors with 4, (6) or 8 lead wiring	
Supply voltage	Controller and motor: 24 to 48 $V_{\text{DC}}$ ; Limit switches and outputs: 24 $V_{\text{DC}}$	
Phase current	Up to 1.7 A <sub>PEAK</sub>	
Step resolution	1/1, 1/2, 1/4, 1/5, 1/8, 1/10, 1/20; for smoother motor rotation: 1/32, 1/64, 1/128 up to 1/256 step of a full step	
Step frequency	40,000 steps/sec	
Physical resolution	Approx. 51,200 positions per revolution (0.007°/step) with a 200 step motor. An encoder with a counter should be considered for very fine positioning.	
Hardware error detection	<ul> <li>Short circuit (between phase and power supply; between both phases; within a motor against ground))</li> <li>Over temperature</li> <li>Under voltage</li> </ul>	
Cable length	Motor: shielded: 50 m max. Signal: shielded: 100 m max.	
Diagnostic LEDs	Ready, busy, ERROR	
Operating mode	"Remote" - via bus; "Local" - stand-alone mode with sequence program	
Interfaces		
Analog outputs	2 x (A, B, C, D) for two 2 phase stepper motors	
Digital outputs	8 digital outputs, overload-proof, each electrically isolated from power supply / 24 V power supply fed separately; the maximum load is 1 A on each output; 4 A for all outputs	
Host interfaces	Optional: USB, Ethernet, RS 485, RS 232	
Analog inputs	2 x 10 Bit AD converter e. g. for a joystick. The joystick power (5 V <sub>DC</sub> ; 100 mA max.) is provided by the controller	
Digital inputs	<ul> <li>8 digital inputs, electrically isolated, 24 V input level</li> <li>4 limit switches: type PNP NCC or NOC</li> <li>2 encoders for optional differential incremental encoder or SSI absolute encoder; provided by the controller (5.3 V<sub>DC</sub>, max. 200 mA)</li> <li>2 Motor Enable</li> </ul>	
Communication and Programming		
Programming	MiniLog format acc. to DIN 66025 – MiniLog-Comm <sup>®</sup> (included in delivery) – LabVIEW <sup>®</sup> VIs (included in delivery)	
Memory	128 kB program memory	
Operating Conditions		
Temperatures	Operation: 5 to 50 °C; storage and transport: -10 to +85 °C	
Degree of pollution	Level 2	
Relative humidity	5 to 85 %, class 3K3 non-condensing	
Protection class	IP 20	
EMC immunity/ EMC emission	Acc. EN 61000-3-2 Acc. EN 61000-6-1, -3, -4 Acc. EN 6100-4-26, -11	
Approval	CE	









Type	ge ion ng tor
¢	uurent/Chopp Malorvali Siep resolu Hust inter Mauni Terminal adap
MCC-2 LIN - 20	- 48 MINI - <mark>USB</mark> - W - B
JSB ETH RS 485 RS 485-USB RS 232	USB port Ethernet port RS 485/4-wire port RS 485/4-wire + USB converter RS 232 port
N H	Wall mounting With attached clip for DIN rail mounting
В	RS 232 adaptor for BT 5 operator terminal
	GB TH 5 485 5 485 5 485-USB 5 232

LabVIEW® is a trade mark of National Instruments Corporation.

MiniLog-Comm<sup>®</sup> is a trade mark of Phytron GmbH.

## **Extent of Supply**

- A CD-ROM with MiniLog-Comm<sup>®</sup> software, LabVIEW<sup>®</sup> VIs and USB driver
- Connector set

# **Optional Accessories**

- Cable assembly
- Power supply unit SPH 240-4805
- BT 5 operator terminal
- Mini USB-RS 485 converter

#### Phytron GmbH

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# MCC-1 Programmable controller for one axis

www.phytron.eu/MCC-1

The MCC-1, phytron's freely programmable dual axis stepper motor controller, is a compact stand-alone unit for 2 phase stepper motors providing up to  $3.5 A_{\text{PEAK}}$  phase current.

Controllers in the MCC series have many inputs and outputs (digital and analogue) and encoder inputs for step position monitoring plus possibilities to connect limit switches all as standard.

Due to the viariety of available host interfaces (USB, Ethernet etc.), the MCC can be quickly

and easily integrated into existing applications.

This controller is easy to program and can operate either directly (remote) via its bus or stand-alone (local) with the program routines stored within.

Applications

As a compact stand-alone device, it convinces expecially in small experimental setups, machines and equipment, which can be dispensed in a PLC.

#### Highlights

ENG



#### Stand-alone

Once programmed the MCC-1 can work without additional PC/controller.

#### All-in-one solution



Stand-alor

A compact device with controller, I/O and power stage by 55 x 127 x 110 mm

#### LabVIEW<sup>®</sup>

LabVIEW<sup>®</sup> is a simulation software with a graphical interface. Use the VIs (Virtual Instruments) generated by phytron and integrate them in your LabVIEW<sup>®</sup> project. So you can easily control the MCC from your usual programming environment.

#### MiniLog-Comm®

MiniLog-Comm<sup>®</sup> is phytron's communication software running under Windows<sup>®</sup> to facilitate programming of the stepper motor controller. It provides quick and easy generation of sequential programs.

The MiniLog-Comm<sup>®</sup> software is delivered free with phytron controllers and offers additional functions for test mode, step by step control or single sequence command execution of a motor move, a motor status window and even a Motion Creator.



- 1 axis stepper motor control unit with integrated power stages
- Bipolar control of 2 phase stepper motors
- Phase currents up to 3.5 A<sub>PEAK</sub>
- Power supply 24 to 48 V<sub>DC</sub>
- Step resolution 1/1 up to 1/256 step
- Host interfaces: USB, Ethernet, RS 485 or RS 232
- Interfaces:
  - 1 encoder
  - 1 analogue input
  - 8 bidirectional, digital inputs and outputs
  - 2 limit switches
  - 2 redundant designed enable inputs
- Programming in well-tried MiniLog format, acc. to DIN 66025 or in LabVIEW<sup>®</sup>
- LabVIEW<sup>®</sup> driver for including the MCC in your LabVIEW<sup>®</sup> project
- Remote or local mode



Specification		
Mechanical		
Dimensions (W x H x D)	55 x 127 x 110 mm; 73 x 127 x 110 mm with attached USB converter or terminal adaptor	
Weight	Approx. 660 g	
Mounting	Wall or rail mounting	
Features		
Stepper motors	Suitable for the control of 2 phase stepper motors with 4, (6) or 8 lead wiring	
Supply voltage	Controller and motor: 24 to 48 $V_{\text{DC}}$ ; Limit switches and outputs: 24 $V_{\text{DC}}$	
Phase current	Up to 3.5 A <sub>PEAK</sub>	
Step resolution	1/1, 1/2, 1/4, 1/5, 1/8, 1/10, 1/20; for smoother motor rotation: 1/32, 1/64, 1/128 up to 1/256 step of a full step	
Step frequency	40,000 steps/sec	
Hardware error detection	<ul> <li>Short circuit (between phase and power supply; between both phases; within a motor against ground))</li> <li>Over temperature</li> <li>Under voltage</li> </ul>	
Cable length	Motor: shielded: 50 m max. Signal: shielded: 100 m max.	
Diagnostic LEDs	Ready, busy, ERROR	
Operating mode	"Remote" - via bus; "Local" - stand-alone mode with sequence program	
Interfaces		
Analog outputs	A, B, C, D for a 2 phase stepper motor	
Digital outputs	8 digital I/Os - programmable as in- or output - overload-proof, each electrically isolated from power supply / 24 V power supply fed separately; the maximum load is 1 A on each output; 4 A for all outputs	
Host interfaces	Optional: USB, Ethernet, RS 485, RS 232	
Analog inputs	2 x 10 Bit AD converter e. g. for a joystick. The joystick power (5 $V_{DC}$ ; 100 mA max.) is provided by the controller	
Digital inputs	<ul> <li>8 digital I/Os - programmable as in- or output - electrically isolated, 24 V input level</li> <li>2 limit switches: type PNP NCC or NOC</li> <li>1 encoders for optional differential incremental encoder or SSI absolute encoder; provided by the controller (5.3 V<sub>DC</sub>, max. 200 mA)</li> <li>2 Motor Enable</li> </ul>	
Communication and Programming		
Programming	MiniLog format acc. to DIN 66025 – MiniLog-Comm <sup>®</sup> (included in delivery) – LabVIEW <sup>®</sup> VIs (included in delivery)	
Memory	128 kB program memory	
Operating Conditions		
Temperatures	Operation: +5 to +50 °C; storage and transport: -10 to +60 °C	
Degree of pollution	Level 2	
Relative humidity	5 to 85 %, class 3K3 non-condensing	
Protection class	IP 20	
EMC immunity/ EMC emission	Acc. EN 61000-3-2 EMC Acc. EN 61000-6-1, -3, -4 EMC and RFI immunity Acc. EN 6100-4-26, -11 Immunity testing	
Approval	CE	


Dimensions in mm

Block Diagram



Configurations





## **Extent of Supply**

- A CD-ROM with MiniLog-Comm<sup>®</sup> software, LabVIEW<sup>®</sup> VIs and USB driver
- Connector set

## **Optional Accessories**

- Cable assembly
- Power supply unit SPH 240-4805
- BT 5 operator terminal
- Mini USB-RS 485 converter

## **Phytron GmbH**

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MiniLog-Comm<sup>®</sup> is a trade mark of Phytron GmbH.

# DRIVES

Drives contain so-called indexers and power stages. You put instructions in a programming language to control signals, which boosts the internal power stage.





Stepper motor module with integrated power stage for the SIMATIC ET  $200^{\odot}\,\mathrm{S}$ 





# 1–STEP–DRIVE–5A–48V Stepper motor module for the SIMATIC ET 200<sup>®</sup>S

## In coordination with SIEMENS

The 1-STEP-DRIVE-5A-48V is a stepper motor controller with integrated power stage. It is specially developed for application in the decentralised SIMATIC ET 200<sup>®</sup>S peripheral system.

This 1-STEP-DRIVE module is configured via mouse click with the STEP<sup>®</sup>7 by using the provided configuration files and then parameterised. The module is ready for use in a very short time and supplements the

SIMATIC ET 200<sup>®</sup>S with a fully integrated, powerful and high-precision positioning controller for 2 phase stepper motors.

#### Application

Application examples for the 1-STEP-DRIVE module are assembly and transfer lines, building automation, x-y-tables, paper mills, printing and textile machines.

## Highlights

#### **Online parameterisation**

These Phytron power stages are eminently suitable for not only setting the basic parameters via interface bus, but also the technological parameters found in the application.

The power stage can be optimised for the requirements of the drive system during commissioning. Furthermore it is possible to adjust the power stage during 'CPU RUN', particularly for the next program sequence.

For example, raise the stop current when the motor is holding a load and then reduce it as soon as the system comes to a standstill without the load to minimize the power requirement and motor heating. Using these functions combined with additional parameters bring out the best in your system.

## Fine positioning to 1/512 step

Almost all commercially available stepper motor power stages can be operated in micro step mode. When driving the motor with encoder feedback, it is apparent that certain micro step positions cannot often be reached because of a lack of fine current settings and the motor may not reach the desired position. The 1-STEP-DRIVE technology guarantees a high-precision current



adjustment and enables fine positioning up to 1/512 step. The diagram above shows that a Phytron 200 step motor with encoder is able to be at each 1/512 micro step position with an absolute and non-cumulative error of about 0.0015°, typically much less than this.

	In Focus
In	tegrated Driver
	The 1-STEP-DRIVE-5A-48V module successfully completed the system compliance test performed by SIEMENS.
	<ul> <li>Stepper motor controller with an integrated power stage for SIMATIC ET 200<sup>®</sup>S</li> <li>For 2 phase stepper motors</li> <li>5 A<sub>PEAK</sub> at 24 to 48 V<sub>DC</sub></li> <li>Up to 1/512 microsteps</li> <li>Online controller parameterisation and diagnostics</li> <li>STEP<sup>®</sup>7 programming</li> </ul>
	SIMATIC ET 2005 IND INI INI INI INI INI INI INI INI INI



Overview

	Specification	
	Mechanical	
		CHATIC FT COORC I
	Design	SIMATIC ET 200°S plastic housing
	Dimensions (W x H x D)	30 x 81 x 50 mm
	Weight	80 g
	Mounting position	Uptional
	Mounting	Plug-in in SIMATIC ET 200°S terminal modules
	Features	
	Stepper motors	Suitable for bipolar control of 2 phase stepper motors with 4, (6) or 8 lead wiring
	Superior main station	SIMATIC ET 200 <sup>®</sup> S
	Power supply	24 to 48 V <sub>DC</sub>
	Reverse polarity protection	Yes
	Phase current	5 A <sub>PEAK</sub> (short circuit-proof, overload protected)
	Motor current adjustment	20 mA increments
	Step resolutions	Full step, half step, 1/2.5, 1/4, 1/5, 1/8, 1/10, 1/16, 1/20, 1/32, 1/64, 1/128, 1/256, 1/512 microstep
	Maximum step frequency	510,000 steps/s
	Physical resolution	Approx. 102,400 positions per revolution (0.0035°/step) with a 200 step motor. An encoder with a counter should be considered for very fine positioning.
	Chopper frequency	18, 20, 22 or 25 kHz selectable Patented phytron chopper technology for a minimal heat loss in the motor and smooth rotation.
	Current consumption (max.)	3 A <sub>DC</sub> at 5 A <sub>PEAK</sub>
	Mechanical output power	Up to the 200 W range
	Cable length - motor	Shielded: 50 m max.
	Cable length - digital inputs	Shielded: 100 m max.
	Diagnostic LEDs	<ul> <li>SF (group error)</li> <li>DRV OK (power stage ready)</li> <li>RDY (module ready)</li> <li>POS (driving instruction is running)</li> <li>3 (digital input IN0 active)</li> <li>7 (digital input IN1 active)</li> <li>TEMP (over temperature &gt; 85 °C)</li> <li>SCO (over current &gt; 10 A)</li> <li>RUN (motor is running)</li> </ul>
	Controller modes	<ul> <li>Relative positioning</li> <li>Move to a reference point</li> <li>Absolute positioning</li> <li>Revolution mode</li> <li>Reference setting</li> </ul>
	Security modes	Security modes, such as e. g. Safe Torque Off (STO) from IEC 61508-2 are not directly compatible
	Mechanism of the communication via backplane bus	Synchronous:         Control interface, feedback interface           Asynchronous:         PLC in CPU STOP mode:         basic parameterising           PLC in CPU RUN mode:         data set transfer







Diagnostic LEDs



Connection diagram



Parameterisation

## Specification

## Features (continued)

realures (continueu)				
Support of linear and modulo axes (rotary axes)	Yes			
Hardware error detection	<ul><li>Over current, sho</li><li>Over temperature</li></ul>	ort circuit >10 e at the powe	) A spike at th r stage T > 8	ie controller 5 °C
Refresh rate	2 ms			
Interfaces				
Analogue outputs	A, B, C, D - For a 2 p	phase steppe	r motor	
Digital inputs	2 configurable digit 0 signal: -30 to 5 V o 1 signal: 11 to 30 V Input delay: 4 ms INO: • External release • External stop • Limit switch towa IN1: • Reference switch forward / reverse • Limit switch conf	al inputs INO with 2 mA ma with 9 mA typ of momentur ards forward and also limi	and IN1: ax. (quiescent pical m / reverse it switch towa pen / close	current) rds
Backplane bus and module supply	Backplane bus of th Module supply via E	ne ET 200®S ET 200®S pow	ver module	
Compatible SIEMENS terminal modules for the 1-STEP-DRIVE	Terminal module TM-E30S46-A1 TM-E30C46-A1 TM-E30S44-01 TM-E30C44-01	Order numb 6ES7193-40 6ES7193-40 6ES7193-40 6ES7193-40	Der CF40-0AA0 CF50-0AA0 CG20-0AA0 CG30-0AA0	Terminals screw with AUX spring with AUX screw without AUX spring without AUX
Compatible SIEMENS power modules	Power module for t DC 24V-48V with dia DC 24V-48V, AC 24 diagnostic and prot	he ET 200 <sup>®</sup> S agnostic - 230 V with ection	Order numb 6ES7138-40 6ES7138-40	eer CA50-0AB0 SIMATC DP CB11-0AB0 SIMATC DP
Communication and Pr	rogramming			
Programming	Via STEP®7			
Control interface (synchronous)	Parameter assignm Basic frequency F Multiplier i (ramp Multiplier n (start Positioning Move to a referen Set home position Relative incremet Absolute incremet Revolution mode Reference setting	n <b>ents</b> F <sub>b</sub> )) t-stop) nce point n ntal mode (re ental mode (a	elative positio absolute posit	ning) tioning)
Feedback interface (synchronous)	Configurable • Residual path • Absolute position • Velocity Also included in the • Position reached • Parameterization • Power stage erro • Limit switch caus • and other states	ing e feedback n error r ses a stop		

## Specification

Communication and Programming (continued)		
Data set transfer to the 1-STEP-DRIVE (asynchronous while CPU RUN)	Parameterising the 1-STEP-DRIVE power stage • Step resolution (1/1, 1/2 up to 1/512) • Preferred direction of rotation • Run current (20 mA increments) • Stop current (20 mA increments) • Boost current (20 mA increments) • Current delay time 1 up to 1000 ms • Chopper frequency 18 to 25 kHz • Switching frequency overdrive 1 to 40 kHz • ODIS behaviour	
Data set transfer from the 1-STEP-DRIVE (asynchronous)	Diagnostics Feedback of the following driver parameters to the main station • Reverse reading controller parameter • Basic position • Error (short circuit, over temperature, parameterizing error)	
Operating Conditions		
Operating temperature	0 to +60 °C	
Storage and transport temperatures	-40 to +70 °C	
Relative humidity	95 % max. non-condensing	
Degree of pollution	Level 2	
Protection class	IP 20	
Vibration / Shock protection	According to EN 60068-2-6 According to EN 60068-2-27/29	
EMC immunity / EMC emission	According to EN 61000-6-2 According to EN 61000-6-4	
Approval	CE	





Communication mechanism

#### Extent of Supply

- 1-STEP-DRIVE module
- CD-ROM incl. configuration file (HSP), application example and PDF manual

## **Optional Accessories**

Manual as printout (ID No.: 10013573)

## Phytron GmbH

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# **POWER STAGES**

Stepper motor power stages reinforce Control pulses/Motor direction or SIN/COS signals and directly control the stepper motor.





APS

High performance stepper motor power stage module





19" stepper motor power stage module with ServiceBus



 $\mathsf{MCD}^{+}$ 

Compact stepper motor power stage with ServiceBus



MSX

19" stepper motor power stage module for high performance



SLS

19" sub-rack with plug-in stepper motor power stage modules





# APS Technology High performance stepper motor power stage Now as OEM module with sin/cos via SPI

The phytron APS module is a high performance power stage for the operation of stepper motors up to 5  $A_{\text{PEAK}}$  at 24 - 70  $V_{\text{DC}}$  with a shaft power up to 250 Watts.

While almost any commercially available stepper motor power stage provides the setting of the so-called microstep operation, the generated current settings are too inaccurate to achieve the individual sub-steps and to approach the actual position.

The APS module positions with an actual step resolution of 1/512 (102,400 positions per revolution with an encoder with a 200 step motor). Based on our parameterisable chopper technology and by the use of premium components with low resistance, the APS triggers with optimal timing. So the APS technology creates a current

shape close to a perfect sine wave with a minimum of heat loss in the controller. Only this highly accurate output signal enables the loss- and low resonance operation of the motor, the fast execution of each sub-step and the approach to each position.

The compact APS is the core of the 1-STEP-DRIVE (for SIMATIC ET 200<sup>®</sup>S) SPS module and as a power stage module of our phyMOTION<sup>TM</sup> available. The APS can be parameterised (run current, stop current, boost current, current delay time etc.) and diagnosed online by a ServiceBus code and is also open for instructions from the CPU in runtime within a parameterisation cycle.

Benefit from our APS power stage technology: EVA-APS board (p.3) or APS-Arduino Shield (p.4).

	Snacification !		
	Specification		
	Mechanical		
	Design		Plug-in power stage module also as OEM module
	Dimensions (W x H)		60 x 40 mm
	Weight		16 g
	Features		
	Stepper motors		Suitable for bipolar control of 2 phase stepper motors with 4-, (6-) or 8 lead wiring
	Phase current		Up to 5 A <sub>PEAK</sub> (short circuit-proof, overload protected)
	Power supply		24 to 70 $V_{DC}$
	Reverse polarity protecti	on	No

Specification - continuation box next side

# Now available for Arduino !

## In Focus

- OEM power stage module with control pulses/direction or sin/cos presetting via SPI
- For 2 phase stepper motors
- Up to 5  $A_{PEAK}$  at 24 -70  $V_{DC}$
- Up to 1/512 step resolution
- Up to 500,000 steps/sec
- Online parameterising and diagnostic of the power stage via Serial Periphal Interface (SPI)
- Control via Control pulses/direction or via digital sin/cos (via SPI)
- Free available parameterisation and diagnosis tool ServiceBus-Comm<sup>®</sup>
- 2 development environments: - for industry: EVA-APS board
  - for research: APS-Arduino Shield



 $\begin{array}{l} \mbox{Violet = Phase current 1} \\ \mbox{Green = Phase current 2} \\ \mbox{1/128-Ministep, 3.5 } A_{RMS} \mbox{(approx. 5.0 } A_{PEAK}), \\ \mbox{U}_B = 60 \mbox{ V} \end{array}$ 



Specification		
Features (continued)		
Motor current adjustment	10 mA current resolution	
Step resolutions	Full step, half step, 1/2.5, 1/4, 1/5, 1/8, 1/10, 1/16, 1/20, 1/32, 1/64, 1/128, 1/256, 1/512 microstep	
Maximum step frequency	500,000 steps/sec	
Physical resolution	Approx. 102,400 positions per revolution (0.0035°/step) with a 200 step motor. An encoder with a counter should be considered for very fine positioning.	
Chopper frequency	18, 20, 22 or 25 kHz selectable Patented phytron Chopper technology for a minimal heat loss in the motor and smooth rotation.	
Current consumption (max.)	3 A <sub>DC</sub> at 5 A <sub>PEAK</sub>	
Mechanical output power	Up to the 250 W range	
Cable length	Motor: shielded: max. 50 m	
Diagnostic LEDs	Opportunity to connect on 2 signal lines with 3.3 V logic level: LED 1 (power stage ready), LED 2 (error)	
Hardware error detection	<ul> <li>Overcurrent, short circuit &gt; 10 A</li> <li>Overtemperature T &gt; 85 °C</li> </ul>	
Interfaces		
Analogue outputs	A, B, C, D, for a 2 phase stepper motor Analogue temperature output: 0 to +90 °C at 480 to 1884 mV	
Digital inputs	Control pulses, Motor direction, Boost, Deactivation, Reset SPI bus interface: • digital sin/cos presetting (alternative to Control pulses/Motor direction) • online parameterisation and diagnostic	
Operating Conditions		
Temperature	Operation: 0 to + 60 °C; storage and transport -40 to +70 °C	
Relative humidity	Max. 95 % non-condensing	
Development Environment		
EVA-APS	Evaluation board for industry	
APS-Arduino Shield	Application platform for research, hobby and art	

Ordering Code	
	2. De
Ordering code	APS01



## Functions

EVA-APS is an evaluation board for application development of the APS power stage and can be ordered as a bundle with the APS power stage.

- Online parameterising and diagnostics via USB
- Control via Control Pulses/Direction
- Two operating modes
- Input signals defined by jumpers
  Customised SPI interface
- ServiceBus-Comm software included

## **Operation/Connection**

Motor voltage supply	24 $V_{\text{DC}}$ to 70 $V_{\text{DC}}$ Input range of supply of the power stages and to generate internal logic voltages
USB interface	For parameterising the APS power stage
Analogue outputs (motor)	A, B, C, D for a 2 phase stepper motor
SPI interface (ST1)	10-pole (2x5), pads for mounting a customised connector
Control pulses/direction interface	25-pole SUB-D connector female, opto-decoupled
PCB connectors 2x10 and 2x12 pins	2 mm grid; 0.5 mm pin Pins: 2x10 and 2x12 for APS power stage connection
2 Program pushbuttons	START: for motor running RESET: Reset of the settings
1 Rotary switch (Function)	Setting of the operating mode
9 Jumpers	For input signal specification



Ordering Code	<u> </u>	
	<i>Type</i>	
Ordering code	EVA-APS (incl. APS)	



## Description

APS-Arduino shield is a development environment for the use of the APS power stage in research, prototyping, model making and art installations.

- APS power stage parameterising and diagnostics via SPI interface
- Control pulses/direction signal comes from the digital pins of the Arduino
- Download of the demo program and description from the phytron website
- Learn more about Arduino: www.arduino.cc

## **Operation/Connection**

Motor voltage supply	24 $V_{\text{DC}}$ to 70 $V_{\text{DC}}$ Input range of supply of the power stage
Analogue outputs (motor)	A, B, C, D for a 2 phase stepper motor
SPI interface	For parameterising and diagnostics of the power stage
Control pulses/direction interface	Control pulses/direction signal from the digital pins of the Arduino
PCB connectors (APS) 2x10 and 2x12 pins	2 mm grid; 0.5 mm pin Pins: 2x10 and 2x12
Pushbutton	Reset of the Arduino



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**INDUSTRIA** 

# ZMX<sup>+</sup> Stepper motor power stage with ServiceBus

The ZMX<sup>+</sup> is a plug-in stepper motor power stage for 19" sub-racks with ServiceBus for motor currents up to 9  $A_{PEAK}$ .

www.phytron.eu/ZMXplus

Due to improved design and greatly reduced power dissipation, the ZMX<sup>+</sup> provides reliable high-precision performance with minimised heat emission.

Parameters can be manually set by switches. The ServiceBus interface allows several additional adjustments.

## Highlights

ENG

## ServiceBus Instruction

ServiceBus Online setting of parameters CAN, RS 485...

## 1/512 Microstep

precise power adjustment and fine positioning up to 1/512 microstep

## **Electrical Isolation**



Integrated Driver

with and without electrical isolation of the motor circuit

## Application

The ZMX<sup>+</sup> is used in different fields of application: e.g. in inspection and test applications, labelling or packaging machines, in equipment manufacturing or in beamlines.

The ZMX<sup>+</sup> version with a 32 pin VG connector is pin compatible with commercially available power stages. The optional ServiceBus connector is placed at the front.

## ServiceBus-Comm<sup>®</sup>

The royalty-free ServiceBus protocol with its extensive command set allows direct communication between phytron power stages and the PC or controller connected — even from a distance. That way not only start, stop and boost current but also parameters like current delay time can be set easily.

Our free Windows<sup>®</sup> software ServiceBus-Comm<sup>®</sup> allows to monitor and to adjust up to 32 axes while providing a comfortable and easy to use graphical interface.



Integrated Driver ServiceBus El. Isolated

- 19" sub-rack power stage for bipolar control of 2 phase stepper motors
- Up to 9  $A_{\text{PEAK}}$  at 24 70  $V_{\text{DC}}$
- Up to 1/512 microsteps
- Parametrising and diagnostic online via ServiceBus — switches for basic adjustment
- Options:

In Focus

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Phytron

ZMX<sup>+</sup>

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Phytron

ZMX<sup>+</sup>

Status

-

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- 32/48 pin connector
- With/without electrical isolation
- With/without ServiceBus



Phytron Extreme. Precision. Positioning.

Specification	
Mechanical	
Design	Plug-in board for 19" sub-rack in the format 5HP x 3U x 160 mm
Dimensions (W x H x D)	Option with 32 pin VG connector: 25.1 (5HP) x 128.4 (3U) x 172.5 mm Option with 48 pin VG connector: 25.1 (5HP) x 128.4 (3U) x 176 mm
Weight	Approx. 450 g with front panel
Features	
Stepper motors	Suitable for the control of 2 phase stepper motors with 4, (6) or 8 lead wiring
Supply voltage	24 to 70 V <sub>DC</sub>
Phase current	2 х 9 А <sub>РЕАК</sub>
Adjustable current steps	Rotary switch mode 2 currents are selectable: 0 – 1.5 A <sub>PEAK</sub> or 0 – 9 A <sub>PEAK</sub> Run current is adjustable in 15 current steps, stop current is 50 %, boost current is 130 % of run current ServiceBus mode (optional) Run, stop and boost current from 0 – 9 A <sub>PEAK</sub> in 100 mA stages
Adjustable step resolution	Rotary switch mode Full step, 1/2, 1/2.5, 1/4, 1/5, 1/8, 1/10, 1/20 ServiceBus mode (optional) Full step, 1/2, 1/2.5, 1/4, 1/5, 1/8, 1/10, 1/16, 1/20, 1/32, 1/64, 1/128, 1/256, 1/512 Microstepping
Maximum step frequency	500,000 Hz control pulse frequency (pulse width > 1 µs)
Physical resolution:	Without encoder: Approx. 25,600 positions per revolution (in typical applications) With encoder: Precision of positioning approx. 102,400 positions per revolution with a a 200 step motor depending on the encoder (evaluating by a superior controller required)
Chopper frequency	Patented phytron chopper technology for a minimal heat loss in the motor and smooth rotation. Two chopper frequencies according to the current range: 25 kHz for currents 0 - 9 A 50 kHz for currents 0 - 1.5 A
Cable length	Motor : shielded: 50 m max. Signal: shielded: 100 m max.
Operating modes	Rotary switch mode and ServiceBus mode (optional)
Functional safety	Safety Integrity Levels, such as e. g. Safe Torque Off (STO) from IEC 61508-2 are not directly compatible
Diagnosable errors	Undervoltage error (< 22 V) Overtemperature error (T > 90 °C) Overcurrent and short circuit error (I > 30 A temporary)
Interfaces	
Inputs	Control pulses, direction, boost, deactivation, reset, step resolution (optional: inputs electrically isolated)
Outputs	A, B, C, D for a 2 phase stepper motor, basic position (opto-decoupled optional, type Open-Collector), ERROR (opto-decoupled optional, type Open-Collector)





32 pin VG connector DIN 41612, type D



48 pin VG connector DIN 41612, type F

## Specification

## Interfaces (continued)

Mechanical switches	Rotary switches for addressing up to 16 addresses DIP-switches for current range selection, ServiceBus activation (optio- nal), output logic switch, overdrive activation and input logic switch		
ServiceBus (optional)	phytron's power stage interface for parameterisation and diagnostic via RS 485		
Communication and Pr	rogramming		
Diagnostic via Status LED	Ready, Busy, Fault, Reset/Disable		
Parameter interface via ServiceBus (optional)	Run, stop, boost current, step resolution, current delay time, chopper frequency, define overdrive switch frequency, in- and output logic, preferential direction, reset, deactivation,		
Diagnostic interface via ServiceBus (optional)	Basic position, current setting, power stage temperature, power stage status, error check, intermediate circuit voltage		
Programming	Phytron's ServiceBus-Comm $^{\odot}$ for Windows $^{\odot}$		
Operating Conditions			
Temperature	Operation: +4 to +40°C, storage and transport: -25 to +85 °C		
Relative humidity	85 % maximum non-condensing		
Degree of pollution	Level 2		
Protection class	IP 20 at operation in 19" rack		
Vibration / Shock protection	Acc. to EN 60068-2-6 Acc. to EN 60068-2-27/29		
EMC immunity / EMC emission	Acc. to EN 61000-3-2 EMC Acc. to EN 61000-6-1, -3, -4: EMC and RFI immudity Acc. to EN6100-4-26, -11 immunity testing		
Approval	CE		

## Plug-in power stage unit SLS-ZMX<sup>+</sup>



phytron delivers also fully assembled 19" sub-rack modules with integrated power supply.

Up to 8  $\mathsf{ZMX}^{*}$  power stages are possible.

For more information look up www.phytron.eu/SLS

Ordering Code		
The variable elements of the product are displayed in colour.	lippe	Electrically isolated
Ordering code	ZMX <sup>+</sup> - 32 -	GT - RS485
Options		
Connector	32 48	32-pin VG connector DIN 41612 (D) 48-pin VG connector DIN 41612 (F)
Electrically isolated I/O	GT	with electrical isolation without electrical isolation
ServiceBus	RS485	ServiceBus via RS 485 without ServiceBus
Windows <sup>®</sup> is a trade mark of Microso	ft	

## Extent of Supply

 Free ServiceBus-Comm<sup>®</sup> software for the ZMX<sup>+</sup> with ServiceBus

## **Optional Accessories**

- Front panel Al 2.5 mm, with handle
- ServiceBus cable
- Mini USB RS 485 converter

ServiceBus-Comm<sup>®</sup> is a trade mark of Phytron GmbH.

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www.phytron.eu



The MCD<sup>+</sup> is a bipolar power stage for driving 2 phase stepper motors. The operation parameters - phase currents, step resolution and preferential motor direction - are programmable by rotary switches or in the ServiceBus mode.

ENG www.phytron.eu/MCDplus

The MCD+ is designed for power supplies from 24 to 70  $V_{\text{DC}}.$ 

The control pulse, motor direction, boost, activation and reset inputs are compatible with push-pull or open collector signals. The control inputs are electrically insulated from the supply and motor voltage. A special feature of the MCD<sup>+</sup> offers 3 terminals for each signal input. Thus separate input terminals for 5 V and 24 V are available.

#### Application

The MCD<sup>+</sup> is suitable for up to 450 Watts of shaft power that is ideal for controlling spindle and toothed belt drive systems for mechanical handling or assembly applications. The high step resolution makes the MCD<sup>+</sup> the best solution for applications that have especially high demands on precision, smoothness and durability.

## Highlights

#### Rotary switch mode

The run and the stop current can be changed between two ranges by the current range switch. These phase currents can be set in 15 increments up to 9  $A_{PEAK}$ . In this operating mode the step resolution can be adjusted from full step up to 1/20 step.



#### Compact design

The complete device plus wall mounting brackets measures only 127 x 37 x 110 mm.

#### ServiceBus instructions

ServiceBus

Online parameterisation even during operation via USB, RS485...

#### ServiceBus mode

All settings are entered at the PC, which is easy to do with the free phytron software ServiceBus-Comm<sup>®</sup> for Windows<sup>®</sup>.

In the ServiceBus mode the phase currents can be programmed in 100 mA increments, the step resolution from full step to 1/512 step and the current delay time from 1 to 1000 ms.





- Stepper motor power stage for bipolar control of 2 phase stepper motors
- Up to 9 A<sub>PEAK</sub> at 24 tp 70 V<sub>DC</sub>

0

- Up to 1/512 step resolution
- Online power stage parameterisation and diagnostic via ServiceBus
- Inputs and outputs are electrically separated
- Optional accessories: USB-RS 485 converter
- Free available parameterisation and diagnosis tool ServiceBus-Comm<sup>®</sup>



Specification				
Mechanical				
Dimensions (W x H x D)	38 x 127 x 110 mm			
Weight	560 g			
Mounting	DIN rail and wall, vertically inside a cabinet is recommended			
Features				
Stepper motors	Suitable for the bipolar control of 2 phase stepper motors with 4, [6] or 8 lead wiring			
Supply voltage	24 to 70 V <sub>DC</sub>			
Phase currents	Up to 9 A <sub>PEAK</sub>			
	Rotary switch mode: Current range selectable by rotary switch: Rotary switch position: I: 0.4 to 3 A <sub>PEAK</sub> , II: 1.1 to 9 A <sub>PEAK</sub> ServiceBus mode:			
	Programmable values: 0.1 to 9 A <sub>PEAK</sub>			
Step resolution	Rotary switch mode: 1/1, 1/2, 1/4, 1/8, 1/10, 1/20 of a full step ServiceBus mode: 1/1, 1/2, 1/4, 1/8, 1/10, 1/16, 1/20, 1/32, 1/64, 1/128, 1/256, 1/512 of a full step			
Cable length	Motor : shielded: 50 m max. Signal: shielded: 100 m max			
Operating modes	Rotary switch mode and ServicBus mode (optional)			
Diagnosable errors	Under-/overvoltage (< 20 $V_{DC}$ or > 85 $V_{DC}$ ), overtemperature (T > 85 °C), overcurrent, short circuit			
Interfaces				
Analogue outputs	A, B, C, D for a 2 phase stepper motor			
Digital outputs	Optically insulated from the motor voltage, type Open-Collector I <sub>max</sub> = 20 mA, U <sub>max</sub> = 30 V, P <sub>total</sub> = 300 mW, U <sub>CE sat</sub> at 20 mA < 1 V Error: short circuit, overvoltage, overtemperature, undervoltage, overcurrent			
Connection	ServiceBus: RS 485, USB-RS 485 converter (optional accessories)			
Inputs	Optically isulated from the motor voltage; control via push-pull driver or Open Collector; input level 5 V or 24 V: Control pulses, Motor direction, Boost, Activation, Reset			
Communication and P	rogramming			
Rotary switch mode	Setting of run and stop current, step resolution and current shape			
DIP switches	Setting of overdrive and boost function, activation and preferential motor direction			
Diagnostic by LED	Basic position, overload, supply failure, overtemperature			
Operating Conditions				
Temperature	Operation: +4 to +40 °C, storage: -25 to +55 °C, transport: -25 to +85 °C			
Degree of pollution	Level 2			
Relative humidity	5 – 85 %. class 3K3 non condensing			
Protection class	IP 20			
EMC immunity / EMC emission	Acc. to EN 61000-3-2: EMC Acc. to EN 61000-6-1, 2, 3, 4: EMC and RFI immunity			
Approval	CE			



Dimensions in mm

0







Ordering Code			
The variable elements of the product are displayed in colour.	Type Current of Current	Judation Mulor routage Sisp resolution Mounting	
Ordering code	MCD <sup>+</sup> 93 -	70 MINI - W	
Options			
Mounting	W H	Wall mounting With attached DIN rail mounting clip	
Windows <sup>®</sup> is a trade mark of Microsoft.			
ServiceBus-Comm <sup>®</sup> is a trade mark of Phytron GmbH.			

## Extent of Supply

- Connector set
- A CD-ROM with ServiceBus-Comm software and USB driver

## **Optional Accessories**

- Rail mounting assembly set with rail mounting clip attached to the housing
- ServiceBus cable
- USB cable
- USB-RS 485 converter
- Power supply SPH 240 or 500 for wall- or rail mounting

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# Supply Failure Sesc Phytron

Zero Signal

Overload

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# MSX Stepper motor power stage for bipolar control

The MSX is a power stage for bipolar control of 2 phase stepper motors. The power stage is available in three power ranges with 5, 10 or 15  $A_{PEAK}$  maximum phase current.

Besides full and half step the MSX provides a resolution up to 1/20 MINI Step.

The setting switch provides several phase current profile settings:

- full step (conventional)
- half step
  - without / with torque compensation
  - without / with Current Shaping
- 1/4 1/20 step
  - without / with Current Shaping
  - with Current Shaping and BLOW UP.

Highlights

## **Current Shaping**

The CS (Curent Shaping) function allows adapting the actual current shape to the selected current curve over a wide frequency range.



## BLOW UP

Improvement of run and acceleration behaviour can be achieved - dependent on the motor type - by the current shape optimising BLOW UP function.

The current regulation by the patented

SYNCHROCHOP principle ensures a smooth

operation of the stepper motor and the

The MSX is suitable to replace the well-tried

older phytron power stages MSO, MSO and

As a powerful stepper motor power stage

the MSX is suitable for up to 800 Watts shaft

power, especially for the handling of discrete

components and machine service tasks as

well as for high-throughput sorting and as-

torque for optimum use.

SMD

Application

sembly machinery.



# In Focus



- Stepper motor power stage for bipolar control of 2 phase stepper motors
- 3 power ranges: 5 / 10 / 15 A<sub>PEAK</sub>
- Supply voltage 60 to 120  $V_{\text{DC}}$  (permissible range 40 to 160  $V_{\text{DC}}$ )
- DIP switches for Overdrive and Boost functions, Activation and Preferential Motor Direction
- Step resolution from full step to 1/20 step



MSX

Specification	
Mechanical	
Dimensions (W x H x D)	70.8 (14HP) x 128.4 (3U) x 188 mm
Weight	Approx. 970 g
Mounting	Designed for installation into 19"/3U sub-racks, 32 pin connector acc. to DIN 41612, version D
Features	
Stepper motors	Suitable for the control of 2 phase stepper motors with 4, (6) or 8 lead wiring
Power range, Phase currents	MSX 52-120: max. 5.1 A <sub>PEAK</sub> MSX 102-120: max. 10.3 A <sub>PEAK</sub> MSX 152-120: max. 15.4 A <sub>PEAK</sub>
Supply voltage	60 to 120 $V_{\text{DC}}$ (permissible range 40 to 160 $V_{\text{DC}}$ )
Adjustable step resolution	Full step, half step, 1/4, 1/10, 1/20 of a full step, with and without torque balance
Cable length	Motor : shielded: 50 m max. Signal: shielded: 100 m max.
Diagnosable errors	Over-/undervoltage (< 40 $V_{DC}$ or > 160 $V_{DC}$ ), overtemperature (T > 85 °C), overcurrent, short circuit
Interfaces	
Analogue outputs	A, B, C, D for a 2 phase stepper motor
Digital outputs	Optically isulated from the motor voltage, type Open-Collector Darlington; I <sub>max</sub> = 20 mA, U <sub>max</sub> = 45 V, UCE <sub>sat</sub> at 20 mA < 0.6 V Basic position, Error
Inputs	All inputs include an optocoupler with series resistors for 5 V or 24 V supply voltage: Control pulse, Motor direction, Boost, Activation, Reset (can be enabled by a jumper)
Communication and P	rogramming
Rotary switches	Setting of run and stop current, step resolution and current shape
DIP switches	Setting of Overdrive and Boost function, Activation and preferential motor direction
Diagnostic by LED	Basic position, overload, supply failure, overtemperature
Operating Conditions	
Temperature	Operation: +4 to +40 °C (we suggest additional cooling with higher operating temperatures) Storage: -25 to +55 °C Transport: -25 to +85 °C
Degree of pollution	Level 2 acc. to EN 50178
Relative humidity	5 – 85 %. class 3K3 non condensing
Protection class	IP 20
EMC immunity / EMC emission	Acc. to EN 50178: high-voltage current Acc. to EN 61000-6-1, 2, 3, 4: EMC and RFI immunity
Approval	CE



Front View

Dimensions in mm



<sup>1]</sup>**Standard version MSX (5 V)** Activation signal: pin 30a and c

Version MSX (5 V-Reset) with Reset input Activation: pin 30a / Reset: pin 30c



phytron also delivers fully assembled 19"rack plug-in units with integrated power supply and optional cooling fan tray.

Up to 4 MSX power stages are possible.

Pin Assignment

## Design Versions

The MSX (120 V type) is available with different phase currents and replaces the following well-tried phytron power stages:

MSX 52 (5 V) MSX 102 (5 V) MSX 152 (5 V)	Standard, replacement for MSO and MSOMINI
MSX 52 (24 V) MSX 102 (24 V) MSX 152 (24 V)	Replacement for SMD
MSX 52 (5 V Reset) MSX 102 (5 V Reset) MSX 152 (5 V Reset)	Additional Reset input (jumper plugged)

Ordering Code				
The variable elements of the product are diplayed in colour.	Type Current regurant/	Matar Jalas Step resolution Optional		
Ordering code	MSX <mark>52</mark> - 120 MINI			
Options				
Peak current / Current regulation	52 102 152	Peak current 5.1 A with SYNCHROCHOP current regulation Peak current 10.3 A with SYNCHROCHOP current regulation Peak current 15.4 A with SYNCHROCHOP current regulation		
Optional	Reset 24 V	Standard MSX (5 V): without additional designation Reset input activated, 5 V input level 24 V input level		

## **Optional Accessories**

- Front panel (14 HP) with handle
- Mating connector with 32 pin connector
- G-MSX adapter board for easy mounting the MSX, with connectors for motor cable, signal leads and supply voltage
- Damping SB 234 module for 90 V
- Damping SB 234 module for 120 V

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# **SLS** 19" sub rack for stepper motor controllers

Phytron's SLS housings are for up to 8 ZMX $^+$  or 4 MSX stepper motor power stages with power supply.

Besides the standard designs we also offer individually configured units, which are designed with phytron's ZMX<sup>+</sup> and MSX power stages for different stepper motor types.

## Application

The SLS was conceived as an all-in-one solution oriented to satisfy the needs of our customers for a 19" format: Power suppy and fans are integrated into the housing according to the requirements in addition to the power stages. With up to 15  $A_{PEAK}$  for each axis, the SLS is prewired, ready for connection, and ideal for demanding multi-axis applications like large manipulators, handling tasks, rapid prototyping or scientific experiments for example in the field of particle accelerators.

In addition, the SLS is the ideal extension for existing controller environments like our modular phy**MOTION**<sup>TM</sup> controller, the standard PLC systems or the PC cards with pulse outputs.

## Highlights

#### Individually designed

The requirements for motor control systems are as individual as its applications.

Depending on customer requirements, the power supply unit is designed with modules and assemblies for signal conditioning and distribution.

Also, a selection of sockets and connectors, pin assignments and cabling are available according to requirements.

Additional functions, e.g. processing and transmission of encoder signals, control of motor brakes or the like can be integrated as needed into the SLS.

## Examples

## SLS with ZMX<sup>+</sup> power stages and ServiceBus

Online parameterisation of the ZMX<sup>+</sup> power stage during the operation via RS 485.

#### SLS with MSX high power stages

Phase currents 5 / 10 / 15 A<sub>PEAK</sub> at 60 to 120 V<sub>DC</sub> bus voltage.







Specification	
Mechanical	
Dimensions (W x H x D)	19" (482.6 mm) x 4 U (177.1 mm) x 370 mm
Weight	Up to 30 kg , depending on the configuration
Mounting	Rack mounting
Features	
Mains connection	115 V <sub>AC ,</sub> 230 V <sub>AC</sub> , 400 V <sub>AC</sub> +/- 10 %, 48 to 62 Hz
Power stages	1 to 8 ZMX <sup>+</sup> with phase currents (with Boost) from either 0 to 1.5 А <sub>РЕАК</sub> ог 0 to 9 А <sub>РЕАК</sub> 1 to 4 MSX with phase currents (with Boost) from 0 to 15.4 А <sub>РЕАК</sub> Custom design available
Stepper motors	Suitable for the control of 2 phase stepper motors with 4, (6) or 8 lead wiring
Cable length	Mains: 2 m max. Motor: shielded: 50 m max. Signal: shielded: 100 m max.
Interfaces	
Signal connectors	Standard: 25-pole DSUB Optional: depending on the signal conditioning and distribution
Motor connectors	Standard: 6 pole connectors acc. to DIN 43652 Optional: according to customer specification
Optional connectors	For ServiceBus: RS 485, RS 232 For limit switch or Encoder connection For temperature sensitive switch for monitoring the mains transformer temperature For more customer specific applications
Communication and P	rogramming
Diagnostics via Status LED of the power stages	Ready, Busy, Reset/Disable, Error diagnostics
Parameterisation via Service- Bus (optional)	Setting of all operating parameters of the ZMX <sup>+</sup> power stage via ServiceBus interface
Operating software	Phytron ServiceBus-Comm <sup>®</sup> for Windows <sup>®</sup>
Operating Conditions	
Temperature	Operation: +5 to +40 °C; storage and transport: -25 to +50 °C
Degree of pollution	Level 2
Relative humidity	5 to 85 %, class 2K3 non-condensing
Protection class	IP 20
EMC immunity / EMC emission	Acc. to EN 61000-3-2 Acc. to EN 61000-6-1, -3, -4 Acc. to EN6100-4-26, -11
Approval	CE



• Outputs: Basic position, Error





/er temperature

 $The \, {\rm SLS}\, is optimally suited \, for \, use \, with \, high$ power stages in combination with the *phy***MOTION**<sup>™</sup> modular 19" sub rack mount controller.

1 Ordering Code Basic Device					
The variable elements of the product are displayed in colour.					
Ordering code	SLS - <mark>115 V</mark>	- 70 V - X			
Options					
Mains voltage	115 V 230 V 400 V	Supply voltage of the SLS			
Motor voltage	40 V 70 V 90 V 120 V	Motor voltage ZMX <sup>+</sup> power stage Motor voltage ZMX <sup>+</sup> power stage Motor voltage MSX power stage Motor voltage MSX power stage			
Options	A AS P X	Signal connector IXE-A compatible Special signal connector IXE-A compatible Signal connector phyMOTION™ compatible Signal connector customised			

Extent of Supply

- SLS- and power stage manual
- Mating connectors

## **Optional Accessories**

- For SLS-ZMX<sup>+</sup> with ServiceBus: A CD with ServiceBus-Comm<sup>®</sup> software, USB driver (included in delivery)
- Cable assembly
- Mini USB-RS 485 converter

For information about mixed configurations (ZMX<sup>+</sup> and MSX) please contact our sales team (sales@phytron.de).

2a Ordering Co	de Assemt	oling wih MSX		
The variable elements of the product are displayed in colour.	Numb.	Peak current reg Current reg Optional		
Ordering code	4	- MSX - <mark>52</mark> -		
Options				
Number of power stages	1 to 4	Number of installable MSX power stages		
Peak current / Current regulation	52 102 152	5.1 A <sub>PEAK</sub> with SYNCHROCHOP current regulation 10.3 A <sub>PEAK</sub> with SYNCHROCHOP current regulation 15.4 A <sub>PEAK</sub> mit SYNCHROCHOP current regulation		
Optional	Reset 24 V	Standard MSX (5 V): without additonal designation Reset input activatd, 5 V input level 24 V input level		

## Ordering Code Assembling wih ZMX<sup>+</sup>

The variable elements of the product are displayed in colour.



## Ordering code

2b

Options	
Number of power stages	1 to 8
Connector	32 48
Electrically isolated I/O	GT
ServiceBus	RS485 CAN



ServiceBus via RS 485 ServiceBus via CAN without ServiceBus



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## www.phytron.eu

# **POWER SUPPLIES**





SPH 240 / 500 / 1013

Power supply for stepper motor power stages and -controllers





www.phytron.eu/SPH

## stages and control units

ENG

The power supply units SPH 240 / 500 / 1013 are used to supply e.g. stepper motor power stages or stepper motor controllers. One power supply can supply several devices, depending on the load.

The SPH 240 can be directly connected to 230 or 115  $V_{AC},$  the mains voltage switch is used to change the voltage range. The SPH 500 and SPH 1013 power supply units switch automatically within the wide range input. The three-phase power supply SPH 1013 has an input range of 3 x 340 to 550  $V_{AC}.$ 

The mains input is internally fused, the output is permanently short circuit-proof. Best operation reliability is ensured by overtemperature protection, overvoltage protection and mains buffering.

A green LED indicates when the 24 V / 48 V or 72 V output voltage is ok.

The built-in fan makes the power supply unit ready for operation in any assembly position.



## In Focus

(mg



- Input voltage range SPH 240 / 500: 90..132 or 180...264 V<sub>AC</sub> SPH 1013: 3 x 340-550 V<sub>AC</sub>
- Output voltage: 24 / 48 / 72 V<sub>DC</sub>
- Output current: 5 to 20 A
- Power category: 240 / 480 / 960 W
- Internally protected mains input
- Permanently short circuit-proof output
- Overvoltage protection primary and secondary side
- Overtemperature protection
- Integrated fan
- DIN rail or wall mounting
- Any mounting position
- Product data sheets and safety instructions are available on the following website: <u>www.mgv.de</u>



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www.phytron.eu

# ACCESSORIES



USB-485 Converter

Interface converter as stick for Phytron stepper motor controllers and power stage





# USB-485 Converter Interface Converter as Stick for Phytron Stepper Motor Controllers and Power Stages

The USB-RS485 stick connects the Phytron RS485 device easily with the standard PC USB-port. The converter is especially designed for the 4-wire RS485 bus (full duplex).

## Connection

The converter is connected to the appropriate controller/power stage directly or by a device-dependent cable.

Before first use the driver must be installed from the Phytron CD.

## **Three Versions**

The stick is available in three versions, which differ in the interface connector:

USB-RS485.4: Connector type USB A for MCC-2, MCC-1 stepper motor controller and MCD+ power stage

USB-RS485.6: 6-pole connector for rack power stages with ribbon cable connector

USB-RS485.9: 9-pole D-sub connector for OMC/TMC stepper motor controller



## In Focus

- Interface converter for Phytron stepper power stages and controllers
- Dimensions: 55 x 30 x 24 cm (without connector)
- Material: ABS, black
- RS485: 4-wire read/write mode up to 32 bus participants maximum, up to 1200 m (incl. bus termination)
- Data rate: up to 2.5 MBit/s
- Power supply: 70 mA (via USB interface)
- Operating systems: Windows Vista, 7, 8, 10
- Accessories, included in delivery:
- Connection cable:
- Type USB A-B, length of 200 cm for all versions
- Type USB A-A, length of 100 cm for USB-RS485.4
- Type 6-pole ribbon cable, length of 20 cm for USB-RS485.6
- Driver CD





Ordering	Code			
Ordering	Coue			
The variable elem the product are dis in colour.	ents of splayed	Converter	Version	
Ordering code		USB-RS485 .	4	
Options				
4	for controllers of M	ICC series and N	MCD⁺ power stage	
6	for rack power stag	ges with 6-pole	ribbon cable connector	
9	for OMC/TMC contr	rollers		

## Phytron GmbH

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# SOFTWARE

Our free WINDOWS<sup>®</sup> programs allow to program, to monitor and to adjust power stages and controllers comfortable and clear via PC.



Development environment for the  $phy MOTION^{\text{TM}}$  stepper motor controller



ServiceBus-Comm®

Communication software for stepper motor power stages





# phyLOGIC<sup>TM</sup> ToolBox Development environment for Stand-alone stepper motor controllers

phyLOGIC<sup>TM</sup> is our new programming language for stepper motor power stages. It is a consistent further development of our proven MiniLog language. It supports on the one hand our established product lines and on the other hand our new modular controller phyMOTION<sup>TM</sup>.

The disclosed  $phyLOGIC^{TM}$  instruction set can be used without license fees and easily integrated into customer applications. With the free development environment  $phyLOGIC^{TM}$  ToolBox, we provide a user friendly software, which can integrate, in addition to its own instruction set, can also integrate the high level C language.

*phy***LOGIC<sup>™</sup>** instructions can be sent individually to the *phy***MOTION<sup>™</sup>** controller directly via various bus protocols, combined into scripts or are stored locally on the controller.

Our ToolBox contains besides the actual programming environment useful tools such as the "Motion Creator" that can easyly draw 2D contours and turn them into code, as well as numerous diagnostic, debugging and testing features.

#### Highlights phyLOGIC<sup>™</sup> in use: Our new modular stepper motor control phyMOTION™ RS485/232/422 ETHERNET CAN PROFIBUS 0 C 0 0 O 0 0 0 0 0 Sx DI Sx DO 8x DI 8x DO Sx DI Sx DC 48 0

## In Focus

- Operating software and development environment for the *phy*MOTION<sup>™</sup> phytron controller
- Easy to program: Drawing and converting from 2D contours in *phy*LOGIC<sup>™</sup> instructions (Motion Creator)
- Parameterising, creating programs, editing, debugging
- Support in the initiation phase e.g. by test functions
- Display of statuses and graphical representation of a current XY position
- Archiving of parameter sets and programs
- Existing MiniLog programs are ported with minimal changes


# Industrial

View Transmission	Controller Options Windows Help		
🕅 🖻 🖻 🖻 🗐	2 C   X B B M   B   ?   🔲 1 Z	3 4 5 6 7 8 9	ABCDEF
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i	×		
MCM			
12 I/O		□ [01] IDXM01	
2 [01] DIOM01		Operation Current setting Status	Power stage temperature
TH Achsen		Motor is running	1: N/A
- [01] IDXM01		Referencepoint reached and	2:
室 A/D		Initiator Negative active	N/A
- 荬 D/A		Initiator Center acitye	N/A
[01] ID     Operation	XM01 E 23	Software limit Negative	N/A
	Existing axes	Power stage error	Motor temperature
	2 + 1 2 3 4 MOP functions	Power stage ready	1:
1-	1+ MOP 1+ MOP 1-	Command is invalid	N/A
	M0P 2+ M0P 2-		2: N/A
	2+ Counter value 1 Cnt: 10		3: N/A
Go	2+         Counter value           1 Cnt:         10           © Relativ         Absolut         1 Enc:         0		3: N/A 4: N/A
Go 1:	2 - Counter value 1 Cnt: 10 © Relativ Absolut 1 Enc: 0 Start 1 Start 2 Cnt: 3		3: N/A 4: N/A
Go 1: 2:	2+         Counter value           1 Cnt:         10           1 Cnt:         10           Start 1         Start           Start 2         2 Cnt:           3         2 Enc:		3: N/A 4: N/A N/A
Go 1: 2:	2 - Counter value 1 Cnt: 10 • Relativ Absolut 1 Enc: 0 Start 1 Start 2 Cnt: 3 Start 2 2 Enc: 0 ! STOP !		3: N/A 4: N/A N/A
Go 1: 2: Frequenc	2+         Counter value           1 Cnt:         10           1 Cnt:         10           Start 1         Start 2           Start 2         Start 2           2 Enc:         0	□ [01] IDXM01	3: NA 4: NA NA
Go 1: 2: Frequenc 1:	2+         Counter value           1 Cnt:         10           1 Enc:         0           Start1         Start           Start2         182           2 Enc:         0           ISTOP !           9         4k           9k         12k           9         4k	[01] IDXM01     [Operation Current setting Status     Ourcent setting axis, 18.2	3: NA 4: NA NA Ourrent settions axis 3 8.4
Go, 1: 2: Frequenc 1: 2:	2*         Counter value           1 Cn::         10           1 Cn::         10           1 Enc:         0           Start 1         Start           Start 2         18:2           2 Enc:         0           I Start 2         18:2           2 Enc:         0           I Start 2         16:2           2 Enc:         0           I Start 2         16:2           2 Enc:         0           I Start 2         16:2           I Start 2         26:4           I Start 2         16:2	I0111DXM01     Operation Current setting Status     Current settings axis 1 & 2     Current settings axis 1	3: NA 4: NA 4: NA Current settings axis 3 & 4 Current settings axis 3 & 4
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Windows<sup>®</sup> is a trade mark of Microsoft.  $phyLOGIC^{TM}$  and  $phyMOTION^{TM}$  are trade marks of Phytron GmbH.

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# ServiceBus-Comm<sup>TM</sup> Communication software for parameterising and control of stepper motor power stages

The phytron communication software Service-Bus-Comm<sup>TM</sup>, designed for Windows<sup>®</sup>, assists the user to program and operate stepper motor power stages – e.g. ZMX<sup>+</sup>, MCD<sup>+</sup>, MR8<sup>+</sup>, CCD<sup>+</sup> – equipped with Service-Bus<sup>1</sup> interface.

Operating parameters such as run current, stop current, step resolution, current delay time or other parameters depending on the type of power stage, can be edited by PC, saved and transmitted to each power stage by ServiceBus.

ServiceBus-Comm<sup>™</sup> helps to monitor the actual current, the power stage- or the motor temperature during operation. Status windows report input conditions and make it possible to set outputs or to display detailed error messages.

Optionally, ServiceBus instructions and functions can be handled by individual software. ReadableASCIIstringinstructions are editable e.g. with LabView<sup>®</sup>, HyperTerminal or C language.

Up to 32 stepper motor axes can be simultaneneously distributed by ServiceBusComm^ $\mathbb{M}.$ 

<sup>1</sup> All types of phytron control units with Service-Bus are labeled by the appendix +.



#### In Focus

- Communication software for stepper motor power stages with ServiceBus
   ServiceBus-Comm<sup>™</sup> is a registered trade mark of the Phytron GmbH.
- Putting into operation, configeration and error diagnosis
- Programming power stage parameters
- Online status display for safe operation and easy maintenance
- Parameter memory for data backup
- Designed for PC under Windows® 95, 98, 2000, NT, XP, 7
- Browser independent installation software
- Installation from CD
- RS 485/4-wire connection of the power stages or ServiceBus modules
- Connection to the PC by USB, RS 485/4-wire or RS 422

## Industrial

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<ul> <li>Power stages</li> <li>PAB</li> <li>MR8+</li> <li>[00] Z5532.200.0,6</li> <li>[01] Z5532.200.1,2</li> </ul>	🗟 [00] ZSS32.200.0,6				
	Axis name				
	Z5532.200.0,6 Set!				
MCD+	Current setting				
CLD+					
₩ ZMX+	Stop cur.: 0	.10 A			
	U U,S I,U I,S Z,U Z,SA	-Save settings			
	Bunour.: 0	.60 A Save actual parameters			
	0 0,5 1,0 1,5 2,0 2,5A	Load basic parameters			
	Boot an . 0	.80 A			
	0 0,5 1,0 1,5 2,0 2,5 A	Transmit settings.			
	More power stage parameters	Power stage short status			
	Step resolution: Current delay time:				
	▶ 1/8 Step 🗢 40 m	Error: Undervoltage			
stage status and test functions unctions	Pref. motor direction: Activation:	Error: Overtemperature			
v, + 1 rev Set basic Rese	e Positive Activat	ed Error: Short circuit in power stage			
Power stage status           Pwr stage - software version:         PAB V2.8 LB           Ready         Output           Under voltage         Output           Over temperature         Total status (HEX)           Short circuit         0030	Input logic level: Copper frequency:	Hardware reset (Watchdog2) Delete			
	Finctellung >> 75 k				
		Power stage in basic position			
	current shape (Cs): Operation mode:	Stat. pwr stage >> Reset power stage			
stage temperature:	Scandard Bus & Swit	cn [ [ ] ] [ ] ] ] ] ] ] ] ] ] ] ] ] ] ]			
25.8 °C					
43.3 V					
I motor current (rms-value):					

phytron products with ServiceBus support:

- MCD+
- MR8<sup>+</sup>
- ZMX+
- PAB<sup>+</sup>
- CLD+
- CCD<sup>+</sup>

Windows<sup>®</sup> is a trade mark of Microsoft. ServiceBus-Comm<sup>™</sup> is a trade mark Phytron GmbH.

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